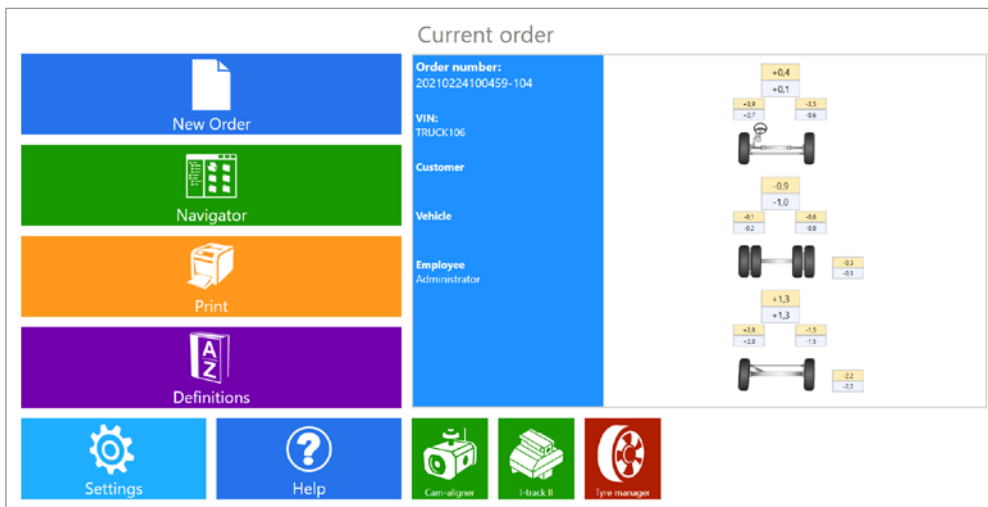


System requirements for Josam homebase 4

Item	Requirement
Operating system	Windows® 10 or 11
Other software requirements	Administrator rights during installation and registration of the software.
Cam-aligner requirements	1 x USB port Wireless server, article # CA1009/CA1009 A (Note: This is included in complete measuring kits). Wireless server driver must be installed prior to software installation.
I-track II requirements	At least Bluetooth 4.0 (LE) built in, 1 x USB port for JOSAM Bluetooth module, article # JT621 (Note: This is included in complete measuring kits).
CPU	64-bit CPU is required. Recommended: <ul style="list-style-type: none"> Intel 8th generation processors (Intel i3/i5/i7/i9-7x), Core M3-7xxx, Xeon E3-xxxx, and Xeon E5-xxxx processors AMD 8th generation processors (A Series Ax-9xxx, E-Series Ex-9xxx, FX-9xxx) Support for ARM64 processors (Snapdragon SDM850 or later) will be implemented during 2025
RAM	At least 4 Gigabyte (GB) of RAM required. 8 Gigabyte (GB) or higher recommended.
Hard disk space	20 Gigabyte (GB) of available hard disk space.
Graphics	WXGA (1366 x 768) or higher resolution video adapter and monitor.
Input devices	Keyboard and Mouse or compatible pointing device.
Other	1 x USB port for software installation. Internet connection required when registering license and for remote support.



The screenshot displays the JOSAM software interface. On the left, there is a vertical menu with buttons for 'New Order', 'Navigator', 'Print', 'Definitions', 'Settings', and 'Help'. Below these are icons for 'Cam-aligner', 'I-track II', and 'Tire manager'. The main area is titled 'Current order' and contains the following information:

- Order number:** 20210224100459-104
- VIN:** TRUCK106
- Customer:**
- Vehicle:**
- Employee:** Administrator

To the right of the text is a diagram of a truck chassis showing wheel alignment data for both front and rear axles. The data points are as follows:

Wheel	Value
Front Left	+0.4
Front Right	+0.1
Rear Left	-0.9
Rear Right	-1.0
Front Left	-0.8
Front Right	-0.7
Rear Left	-0.1
Rear Right	-0.2
Front Left	+1.3
Front Right	+1.3
Rear Left	-0.8
Rear Right	-0.8
Front Left	+2.8
Front Right	+1.3
Rear Left	-2.2
Rear Right	-2.2